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On the macroscopical description of the flow of nonlinear wave equations

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Sobolev spaces

- For a function f on $\mathbb{T}^d = (\mathbb{R}/(2\pi\mathbb{Z}))^d$ given by its Fourier series

$$f(x) = \sum_{n \in \mathbb{Z}^d} \hat{f}(n) e^{in \cdot x},$$

we define the Sobolev norm H^s of f as

$$\|f\|_{H^s}^2 = \sum_{n \in \mathbb{Z}^d} \langle n \rangle^{2s} |\hat{f}(n)|^2.$$

Here $\hat{f}(n)$ are the Fourier coefficients of f and

$$\langle n \rangle = (1 + n_1^2 + \dots + n_d^2)^{\frac{1}{2}}.$$

- For $s \geq 0$ an integer, we have

$$\|f\|_{H^s} \approx \sum_{|\alpha| \leq s} \|\partial^\alpha f\|_{L^2}.$$

The nonlinear Klein-Gordon equation

- Consider

$$(\partial_t^2 - \Delta + 1)u + u^3 = 0, \quad (1)$$

where Δ is the Laplacian and u is a real valued function.

- If we multiply the equation (1) by $\partial_t u$, we formally get

$$\frac{d}{dt} \left(\int (|\nabla u|^2 + u^2 + (\partial_t u)^2 + \frac{1}{2}u^4) \right) = 0.$$

Therefore $(u, \partial_t u) \in H^1 \times L^2$ is a natural framework for the solutions of (1).

The nonlinear Klein-Gordon equation

Theorem 1 (classical)

- For every $(u_0, u_1) \in H^1(\mathbb{T}^3) \times L^2(\mathbb{T}^3)$ there exists a unique global solution of

$$(\partial_t^2 - \Delta + 1)u + u^3 = 0, \quad u(0, x) = u_0(x), \quad \partial_t u(0, x) = u_1(x)$$

in the class $(u, \partial_t u) \in C(\mathbb{R}; H^1(\mathbb{T}^3) \times L^2(\mathbb{T}^3))$.

- If in addition $(u_0, u_1) \in H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)$ for some $s \geq 1$ then

$$(u, \partial_t u) \in C(\mathbb{R}; H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)).$$

The dependence with respect to the initial data is continuous.

- The local in time part of Theorem 1 can be extended to the case $(u_0, u_1) \in H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)$, $s \geq 1/2$, and the global in time part to $s > 3/4$ (Kenig-Ponce-Vega, Gallagher-Planchon, Roy).
- We conjecture that Theorem 1 remains true for $s \geq 1/2$ (related recent work by Dodson).

Limit of the deterministic methods

Theorem 2

Let $s \in (0, 1/2)$ et $(u_0, u_1) \in H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)$. There exists a sequence

$$u_N(t, x) \in C^\infty(\mathbb{R} \times \mathbb{T}^3), \quad N = 1, 2, \dots$$

such that

$$(\partial_t^2 - \Delta + 1)u_N + u_N^3 = 0$$

with

$$\lim_{N \rightarrow +\infty} \|(u_N(0) - u_0, \partial_t u_N(0) - u_1)\|_{H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)} = 0$$

but for every $T > 0$,

$$\lim_{N \rightarrow +\infty} \sup_{0 \leq t \leq T} \|u_N(t)\|_{H^s(\mathbb{T}^3)} = +\infty.$$

- The proof is based on an idea introduced by **Lebeau** and further developed by Christ-Colliander-Tao, Burq-Tz., Xia.

Solving the equation by probabilistic methods

- Inspired by the work of **Bourgain in the early 1990's** on invariant measures for NLS, we can ask whether some form of well-posedness survives for initial data in

$$H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3), \quad s < 1/2. \quad (2)$$

- The answer of this question is positive if we endow the space (2) with a non degenerate probability measure such that we have the existence, the uniqueness, and a form of continuous dependence almost surely with respect to this measure.

Choice of the measure

- Fix a real number σ . We will choose the initial data among the realisations of the following random series

$$u_0^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad u_1^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x}. \quad (3)$$

Here $\{g_n\}_{n \in \mathbb{Z}^3}$ et $\{h_n\}_{n \in \mathbb{Z}^3}$ are two families of independent random variables conditioned by $g_n = \overline{g_{-n}}$ and $h_n = \overline{h_{-n}}$, so that u_0^ω and u_1^ω are real valued.

- In addition, we suppose that for $n \neq 0$, g_n and h_n are complex gaussians from $\mathcal{N}_{\mathbb{C}}(0, 1)$, and that g_0 and h_0 are standard real gaussians from $\mathcal{N}(0, 1)$.
- The initial data (3) belong almost surely to $H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)$ for $s < \sigma - \frac{1}{2}$ ($= \sigma + 1 - \frac{3}{2}$). Moreover, the probability of the event

$$(u_0^\omega, u_1^\omega) \in H^{\sigma - \frac{1}{2}}(\mathbb{T}^3) \times H^{\sigma - \frac{3}{2}}(\mathbb{T}^3)$$

is zero.

Reformulation of the ill-posedness result

Theorem 3

Let $\sigma \in (1/2, 1)$ and $0 < s < \sigma - 1/2$. For almost every ω , there exists a sequence

$$u_N^\omega(t, x) \in C^\infty(\mathbb{R} \times \mathbb{T}^3), \quad N = 1, 2, \dots$$

such that

$$(\partial_t^2 - \Delta + 1)u_N^\omega + (u_N^\omega)^3 = 0$$

with

$$\lim_{N \rightarrow +\infty} \|(u_N^\omega(0) - u_0^\omega, \partial_t u_N^\omega(0) - u_1^\omega)\|_{H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3)} = 0$$

but for every $T > 0$,

$$\lim_{N \rightarrow +\infty} \sup_{0 \leq t \leq T} \|u_N^\omega(t)\|_{H^s(\mathbb{T}^3)} = +\infty.$$

We can however prove the following result:

Theorem 4 (Burq-Tz. (2010))

Let $\sigma \in (1/2, 1)$ and $0 < s < \sigma - 1/2$. Define (thanks to the classical well-posedness result) the sequence $(u_N)_{N \geq 1}$ of solutions of

$$(\partial_t^2 - \Delta + 1)u + u^3 = 0 \quad (4)$$

with C^∞ initial data

$$u_0^\omega(x) = \sum_{|n| \leq N} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad u_1^\omega(x) = \sum_{|n| \leq N} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x}.$$

The sequence $(u_N)_{N \geq 1}$ converges almost surely as $N \rightarrow \infty$ in $C(\mathbb{R}; H^s(\mathbb{T}^3))$ to a (unique) limit u which satisfies (4) in the distributional sense.

- Therefore the type of the approximation of the initial data is crucial when we prove probabilistic low regularity well-posedness.
- Even if we consider the approximation of the initial data by Fourier truncation there is dense set of pathological data such that the statement of Theorem 4 does not hold (recent work by **Sun-Tz.**).
- We can prove uniqueness in a suitable functional framework.
- We can consider more general randomisations (this fact had an important impact in the field).

Going further

Theorem 5 (Oh-Pocovnicu-Tz. (2019))

Let $\sigma \in (\frac{1}{4}, \frac{1}{2}]$ and $s < \sigma - 1/2$. There exists a divergent sequence $(c_N)_{N \geq 1}$ such that if we denote by $(u_N^\omega)_{N \geq 1}$ the solution of

$$\partial_t^2 u - \Delta u + u - c_N u + u^3 = 0, \quad (5)$$

with initial data given by

$$u_{0,N}^\omega(x) = \sum_{|n| \leq N} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad u_{1,N}^\omega(x) = \sum_{|n| \leq N} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x}$$

then for almost every ω there exists $T_\omega > 0$ such that $(u_N^\omega)_{N \geq 1}$ converges in $C([-T_\omega, T_\omega]; H^s(\mathbb{T}^3))$.

- Theorem 5 was the first step in the study of the nonlinear wave equation in Sobolev spaces of negative indexes.
- Recent work by **Bringmann** allows to have $\sigma > 0$ (there are related works by **Gubinelli-Koch-Oh, Deng-Nahmod-Yue**).
- For $\sigma = 0$ there is exceptionally an invariant measure and one may hope to get global solutions by an argument of Bourgain. Solving this problem now only seems a question of time.

A puzzling remark

- Unfortunately, even if these last results are satisfactory as far individual trajectories are concerned, these results give no insight on the macroscopical description of the flow. Namely, we **do not know** what is the transport by the flow of the measure induced by the map

$$\omega \mapsto \left(\sum_{n \in \mathbb{Z}^3} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad \sum_{n \in \mathbb{Z}^3} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x} \right).$$

- It turned out that the answer of the last question of macroscopical description is hard from being obvious even for large σ (gaussian fields with regular typical elements).
- However, as we shall see right now we find easily the answer of the above question for the linear equation.

The linear equation

- Consider the linear Klein-Gordon equation

$$\partial_t^2 u - \Delta u + u = 0, \quad u(0, x) = u_0(x), \quad \partial_t u(0, x) = u_1(x), \quad (6)$$

where u_0 and u_1 are real valued and $u : \mathbb{R} \times \mathbb{T}^3 \rightarrow \mathbb{R}$. The solutions of (6) are given by

$$S(t)(u_0, u_1) \equiv \cos(t\sqrt{1 - \Delta})(u_0) + \frac{\sin(t\sqrt{1 - \Delta})}{\sqrt{1 - \Delta}}(u_1),$$

where

$$\cos(t\sqrt{1 - \Delta})(u_0) \equiv \sum_{n \in \mathbb{Z}^3} \cos(t\langle n \rangle) \widehat{u}_0(n) e^{in \cdot x},$$

$$\frac{\sin(t\sqrt{1 - \Delta})}{\sqrt{1 - \Delta}}(u_1) \equiv \sum_{n \in \mathbb{Z}^3} \frac{\sin(t\langle n \rangle)}{\langle n \rangle} \widehat{u}_1(n) e^{in \cdot x}.$$

The free evolution

- It follows directly from the definition that the operator

$$\bar{S}(t) \equiv (S(t), \partial_t S(t)),$$

where

$$\partial_t S(t)(u_0, u_1) \equiv -\sqrt{1 - \Delta} \sin(t\sqrt{1 - \Delta})(u_0) + \cos(t\sqrt{1 - \Delta})(u_1)$$

is bounded on $H^\sigma \times H^{\sigma-1}$, $\bar{S}(0) = \text{Id}$ and $\bar{S}(t + \tau) = \bar{S}(t) \circ \bar{S}(\tau)$.

- In the proof of the boundedness of $\bar{S}(t)$ on $H^\sigma \times H^{\sigma-1}$, we only use the boundedness of $\cos(t\langle n \rangle)$ and $\sin(t\langle n \rangle)$. One may use the oscillations of $\cos(t\langle n \rangle)$ and $\sin(t\langle n \rangle)$ for $|n| \gg 1$ in order to get more involved L^p , $p > 2$ properties of the map $\bar{S}(t)$ (Strichartz estimates).

Invariant spaces of the linear evolution

Set

$$l_1 = \begin{pmatrix} \cos(n \cdot x) \\ 0 \end{pmatrix}, \quad l_2 = \begin{pmatrix} 0 \\ \cos(n \cdot x) \end{pmatrix}.$$

Then by definition for real numbers λ_1, λ_2 , we can write

$$\begin{aligned} \bar{S}(t)(\lambda_1 l_1 + \lambda_2 l_2) &= (\lambda_1 \cos(t\langle n \rangle) + \lambda_2 \langle n \rangle^{-1} \sin(t\langle n \rangle)) l_1 \\ &\quad + (-\lambda_1 \langle n \rangle \sin(t\langle n \rangle) + \lambda_2 \cos(t\langle n \rangle)) l_2 \end{aligned}$$

Hence in the plane spanned by l_1, l_2 , the map $\bar{S}(t)$ is represented by

$$A = \begin{pmatrix} \cos(t\langle n \rangle) & -\langle n \rangle \sin(t\langle n \rangle) \\ \langle n \rangle^{-1} \sin(t\langle n \rangle) & \cos(t\langle n \rangle) \end{pmatrix}.$$

We have that $\det(A) = 1$ and that for every σ , the quadratic form

$$Q(X, Y) = \langle n \rangle^{2\sigma+2} X^2 + \langle n \rangle^{2\sigma} Y^2$$

is preserved by $\bar{S}(t)$.

Invariant spaces of the linear evolution (sequel)

Let us equip the line spanned by l_1 with the gaussian measure

$$\frac{\langle n \rangle^{\sigma+1}}{\sqrt{2\pi}} e^{-\frac{\langle n \rangle^{2\sigma+2} x^2}{2}} dx,$$

the line spanned by l_2 with the gaussian measure

$$\frac{\langle n \rangle^{\sigma}}{\sqrt{2\pi}} e^{-\frac{\langle n \rangle^{2\sigma} x^2}{2}} dx.$$

Denote by γ the natural product measure in the plane spanned by l_1 and l_2 . Then thanks to the previous discussion, we have :

Proposition 6

The measure γ is invariant under the restriction of $\bar{S}(t)$ to the plane spanned by l_1 and l_2 .

A similar analysis holds concerning the plane spanned by

$$\begin{pmatrix} \sin(n \cdot x) \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ \sin(n \cdot x) \end{pmatrix}.$$

Invariance under the free evolution

Denote by μ_σ the measure induced by the map

$$\omega \mapsto \left(\sum_{n \in \mathbb{Z}^3} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad \sum_{n \in \mathbb{Z}^3} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x} \right).$$

The previous analysis yields :

Proposition 7

Let $\sigma \in \mathbb{R}$. The measure μ_σ is invariant under the linear evolution $\bar{S}(t)$.

Question : How much this property survives for the nonlinear flow ?

The measure μ_σ and the nonlinear equation

- Consider again the nonlinear Klein-Gordon equation

$$\partial_t^2 u - \Delta u + u + u^3 = 0, \quad (7)$$

where $u : \mathbb{R} \times \mathbb{T}^3 \rightarrow \mathbb{R}$.

- We rewrite (7) as the first order system

$$\partial_t u = v, \quad \partial_t v = \Delta u - u - u^3. \quad (8)$$

- One can rewrite (8) as a Hamiltonian system

$$\partial_t u = \frac{\delta E}{\delta v}, \quad \partial_t v = -\frac{\delta E}{\delta u},$$

where

$$E(u, v) = \frac{1}{2} \int_{\mathbb{T}^3} (u^2 + |\nabla u|^2 + v^2) + \frac{1}{4} \int_{\mathbb{T}^3} u^4.$$

- Therefore $E(u, v)$ is a first integral for (8).

Recalling the global well-posedness

- In view of the Hamiltonian structure and the properties of the linear equation, a natural phase space for

$$\partial_t u = v, \quad \partial_t v = \Delta u - u - u^3. \quad (9)$$

is

$$\mathcal{H}^s(\mathbb{T}^3) \equiv H^s(\mathbb{T}^3) \times H^{s-1}(\mathbb{T}^3).$$

Theorem 8 (the classical result again)

Let $s \geq 1$. For every $(u_0, v_0) \in \mathcal{H}^s(\mathbb{T}^3)$ there is a unique solution of (9) in $C(\mathbb{R}; \mathcal{H}^s(\mathbb{T}^3))$.

- Denote by $\Phi(t) : \mathcal{H}^s(\mathbb{T}^3) \rightarrow \mathcal{H}^s(\mathbb{T}^3)$ the resulting flow in Theorem 8.
- **We are interested in the statistical description of $\Phi(t)$.**

Theorem 9 (Gunaratnam-Oh-Tz.-Weber (2019))

Let $\sigma \geq 4$ be an even integer. Then μ_σ is quasi-invariant under the nonlinear flow $\Phi(t)$.

- This result was perviously obtained by Tz. for \mathbb{T}^1 and Oh-Tz. for \mathbb{T}^2 .
- For $d = 1, 2$ we prove more than for $d = 3$.
- For $d = 2, 3$ renormalisation arguments are needed.
- The result of Theorem 9 holds also for the cubic wave equation

$$\partial_t^2 u - \Delta u + u^3 = 0.$$

A corollary

Theorem 10 (a stability property)

Let $\sigma \geq 4$ be an even integer. Let

$$f_1(u, v), f_2(u, v) \in L^1(d\mu_\sigma(u, v))$$

and let $\Phi(t)$ be the flow of

$$\partial_t u = v, \quad \partial_t v = \Delta u - u - u^3,$$

defined μ_σ a.s. Then for every $t \in \mathbb{R}$, the transports of the measures

$$f_1(u, v)d\mu_\sigma(u, v), \quad f_2(u, v)d\mu_\sigma(u, v)$$

by $\Phi(t)$ are given by

$$F_1(t, u, v)d\mu_\sigma(u, v), \quad F_2(t, u, v)d\mu_\sigma(u, v)$$

respectively, for suitable $F_1(t, \cdot), F_2(t, \cdot) \in L^1(d\mu_\sigma)$. Moreover

$$\|F_1(t) - F_2(t)\|_{L^1(d\mu_\sigma)} = \|f_1 - f_2\|_{L^1(d\mu_\sigma)}.$$

Further comments

- The proof crucially exploits the "dispersion" for any σ . More precisely, μ_σ are not quasi-invariant under the flow of

$$\partial_t u = v, \quad \partial_t v = -u - u^3,$$

as shown in a recent work by Sosoë-Trenberth-Xiao.

- I would love to be able to prove that the same result should hold for any $\sigma > 1/2$ (for $\sigma \in (1/2, 1]$ one should use a probabilistic global well-posedness in the sense of Burq-Tz.).

More about the gaussian measures μ_σ

- μ_σ is **formally** defined by

$$d\mu_\sigma = Z_\sigma^{-1} e^{-\frac{1}{2}\|(u,v)\|_{\mathcal{H}^{\sigma+1}}^2} dudv$$

or

$$Z_\sigma^{-1} \prod_{n \in \mathbb{Z}^3} e^{-\frac{1}{2}\langle n \rangle^{2(\sigma+1)}|\hat{u}_n|^2} e^{-\frac{1}{2}\langle n \rangle^{2\sigma}|\hat{v}_n|^2} d\hat{u}_n d\hat{v}_n,$$

where \hat{u}_n and \hat{v}_n denote the Fourier transforms of u and v respectively.

- For $\sigma > 3/2$, it is a gaussian measure on $L^2(\mathbb{T}^3) \times L^2(\mathbb{T}^3)$ with covariance operator

$$((1 - \Delta)^{-\sigma-1}, (1 - \Delta)^{-\sigma}).$$

More about the gaussian measures μ_σ (sequel)

- Our way to define μ_σ rigorously is to see it as the induced probability measure under the map

$$\omega \longmapsto (u^\omega(x), v^\omega(x))$$

with

$$u^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad v^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x}. \quad (10)$$

- The partial sums of the series in (10) are a Cauchy sequence in $L^2(\Omega; \mathcal{H}^s(\mathbb{T}^3))$ for every $s < \sigma + 1 - \frac{3}{2}$ and therefore one can see μ_σ as a probability measure on \mathcal{H}^s for a fixed $s < \sigma + 1 - \frac{3}{2} = \sigma - \frac{1}{2}$.
- For the same range of s , the triplet $(\mathcal{H}^{\sigma+1}(\mathbb{T}^3), \mathcal{H}^s(\mathbb{T}^3), \mu_\sigma)$ forms an abstract Wiener space.

Related results 1 (Cameron-Martin 1944)

Theorem 11 (Cameron-Martin in the context of the measure μ_σ)

For a fixed $(h_1, h_2) \in \mathcal{H}^s$, $s < \sigma - \frac{1}{2}$, the transport of μ_σ under the shift

$$(u_1, u_2) \longmapsto (u_1, u_2) + (h_1, h_2)$$

is absolutely continuous with respect to μ_σ if and only if

$$(h_1, h_2) \in \mathcal{H}^{\sigma+1} .$$

Our result in the context of Cameron-Martin's theorem

- For $(u, v) \in \mathcal{H}^s$, we classically have

$$\Phi(t)(u, v) = \bar{S}(t)\left((u, v) + (h_1, h_2)\right),$$

where $(h_1, h_2) = (h_1(u, v), h_2(u, v)) \in \mathcal{H}^{s+1}$ (one smoothing and not more).

- Clearly if $s < \sigma - \frac{1}{2}$ then $s+1 < \sigma+1$ and therefore our result displays a remarkable property of the vector field generating $\Phi(t)$.
- More precisely, if (h_1, h_2) were independent of (u, v) of regularity \mathcal{H}^{s+1} then the transported measure would not be absolutely continuous with respect to μ_σ !

Related results 2 (Ramer 1974)

- For $s < \sigma - \frac{1}{2}$, let us consider a diffeo Φ on $\mathcal{H}^s(\mathbb{T}^3)$ of the form

$$\Phi(u, v) = (u, v) + F(u, v),$$

where $F : \mathcal{H}^s(\mathbb{T}^3) \rightarrow \mathcal{H}^{\sigma+1}(\mathbb{T}^3)$. Suppose that

$$DF(u, v) : \mathcal{H}^{\sigma+1}(\mathbb{T}^3) \rightarrow \mathcal{H}^{\sigma+1}(\mathbb{T}^3)$$

is Hilbert-Schmidt.

- Ramer (1974) : under the above assumption μ_σ is quasi-invariant under Φ .
- Typical example :

$$F(u, v) = \varepsilon(1 - \Delta)^{-3/2-\delta}(u^2, v^2), \quad \delta > 0, \quad |\varepsilon| \ll 1,$$

i.e. 3-smoothing is needed.

- The Ramer's result would apply in the context of

$$\partial_t^2 u + (-\Delta)^\alpha u + u + u^3 = 0, \quad \alpha > 3.$$

- Therefore our result *seems* to go much beyond Ramer's framework.

Related results 3. (Cruzeiro 1983)

- In her work Ana Bela Cruzeiro considers a general equation of the form

$$\partial_t u = X(u),$$

where X is a vector field on \mathcal{H}^s , $s < \sigma - \frac{1}{2}$.

- A.B. Cruzeiro 1983 : the resulting flow has μ_σ as a quasi-invariant measure provided that several assumptions are satisfied, the most important being

$$\int_{\mathcal{H}^s} e^{\operatorname{div}(X(u))} d\mu_\sigma(u) < \infty. \quad (11)$$

- Very very roughly speaking, our work consists in verifying in practice a conditions of type (11) by exploiting techniques from dispersive PDE's.

A connection with the wave turbulence type problems

- In the WT problems one studies the behaviour of

$$N(n, t) = \mathbb{E}\left(|\mathcal{F}(\Phi(t)(u_0^\omega, v_0^\omega))(n)|^2\right), \quad n \in \mathbb{Z}^3, t \in \mathbb{R}$$

in various limits.

- Our results says that there exists a density (resulting from the quasi-invariance)

$$F(t, \omega) \geq 0, \quad F(t, \cdot) \in L^1(\Omega), \quad F(0, \omega) = 1$$

such that

$$N(n, t) = \int_{\Omega} \left(\frac{|g_n(\omega)|^2}{\langle n \rangle^{2\sigma+2}} + \frac{|h_n(\omega)|^2}{\langle n \rangle^{2\sigma}} \right) F(t, \omega) dp(\omega).$$

- Therefore the density $F(t, \omega)$ (if it exists !) contains all the information needed to know $N(n, t)$. It contains even more information.

A connection with the wave turbulence type problems (sequel)

- Therefore the density $F(t, \omega)$ (if it exists !) contains all the information needed to know $N(n, t)$. It contains even more information.
- Recent work by Debussche-Tsutsumi, Genovese-Luca-Tz. (in progress) and Planchon-Visciglia-Tz. (in progress) allow to know some precise informations on the densities $F(t, \omega)$.
- Therefore it does not seem impossible to me to study the WT limits directly in the densities of the quasi-invariance results. It looks to be an interesting line of research.

A dual formulation

- Denote by $u(t, x, \omega)$ the solution of the nonlinear wave equation with data

$$u_0^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{g_n(\omega)}{\langle n \rangle^{\sigma+1}} e^{in \cdot x}, \quad v_0^\omega(x) = \sum_{n \in \mathbb{Z}^3} \frac{h_n(\omega)}{\langle n \rangle^\sigma} e^{in \cdot x}.$$

- Then there exists a density

$$f(t, \omega) \geq 0, \quad f(t, \cdot) \in L^1(\Omega), \quad f(0, \omega) = 1$$

such that:

$$\int_{\Omega} |\hat{u}_n(t, \omega)|^2 f(t, \omega) dp(\omega) = \langle n \rangle^{-2(\sigma+1)}, \quad \forall n \in \mathbb{Z}^3$$

where $u_n(t, \omega)$ are the Fourier coefficients of $u(t, x, \omega)$.

- I do not know whether this remark may be of some interest in wave turbulence considerations.

Corresponding results for NLS

- In a work by Planchon-Visciglia-Tz. the previous quasi-invariance results are extended to the $1d$ NLS. The NLS is harder than the wave equation because of the lack of direct smoothing. However, we can exploit some hidden smoothing via modified energies ...
- The extension to $2d$ is a challenging problem. Namely can we prove that the measure induced by the map

$$\omega \longmapsto \sum_{n \in \mathbb{Z}^2} \frac{g_n(\omega)}{\langle n \rangle^s} e^{in \cdot x} \quad (12)$$

is quasi-invariant under the flow of the $2d$ NLS

$$i\partial_t u + \Delta u = |u|^2 u ?$$

(which is perfectly well-defined for data given by (12) as far as $s > 2$).

- I would be happy to know the answer of this question even only for very large values of s .

Thank you very much !
(hoping that better times will come soon)