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# Multi-solitons for the water-waves system

based on joint work with

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## The equation

- We study the (infinite dimensional) Hamiltonian equation

$$\partial_t \eta = \frac{\delta E}{\delta \phi}, \quad \partial_t \varphi = -\frac{\delta E}{\delta \eta}, \quad (1)$$

where

$$E(\eta, \varphi) = \frac{1}{2} \int_{-\infty}^{\infty} \left[ (G[\eta]\varphi) \varphi + g\eta^2 + 2b(\sqrt{1 + (\partial_x \eta)^2} - 1) \right] dx.$$

Here  $g$  is the gravity constant and  $b$  the surface tension coefficient.

- $G[\eta]$  denotes a Dirichlet-Neumann map defined as follows. For given "nice"  $\eta, \varphi : \mathbb{R} \rightarrow \mathbb{R}$ , s.t.  $\inf_x \eta(x) > -H$ , we define  $\Phi(x, z)$  as

$$(\partial_x^2 + \partial_z^2)\Phi = 0, \quad \text{in } -H < z < \eta(x),$$

with boundary conditions  $\partial_z \Phi(x, -H) = 0, \Phi(x, \eta(x)) = \varphi(x)$ . Then by definition

$$G[\eta]\varphi = \partial_z \Phi(x, \eta(x)) - \partial_x \eta(x) \partial_x \Phi(x, \eta(x)).$$

- The energy  $E$  is formally conserved by the flow of (1). So is the momentum :  $\int \eta \partial_x \varphi$ . These facts are of crucial importance for our analysis.

## The solitary wave solutions

### Theorem 1 (Amick-Kirchgässner)

Suppose that the speed  $c$  is such that

$$\frac{gH}{c^2} = 1 + \varepsilon^2, \quad \frac{b}{Hc^2} > \frac{1}{3}.$$

Then there exists  $\varepsilon_0$  such that for every  $\varepsilon \in (0, \varepsilon_0)$  (which fixes the speed  $c$ ) there is a solution of the water-wave system under the form

$$Q_c(x - ct) = (\eta_c(x - ct), \varphi_c(x - ct))$$

where  $\eta_c$  and  $\varphi_c$  satisfy:

$$\exists d > 0, \quad \forall \alpha \geq 0, \quad \exists C_\alpha > 0, \quad \forall x \in \mathbb{R}, \quad |\partial_x^\alpha \eta_c(x)| \leq C_\alpha e^{-d|x|}$$

and

$$\exists d > 0, \quad \forall \alpha \geq 1, \quad \exists C_\alpha > 0, \quad \forall x \in \mathbb{R}, \quad |\partial_x^\alpha \varphi_c(x)| \leq C_\alpha e^{-d|x|}.$$

Moreover  $\eta_c$  is even and  $\varphi_c$  is odd.

## Relation with the KdV solitary wave

In fact, we have that

$$Q_c(x) = (\eta_c(x), \varphi_c(x)) = (H\eta_\varepsilon(H^{-1}x), cH\varphi_\varepsilon(H^{-1}x))$$

with

$$\eta_\varepsilon(x) = \varepsilon^2 \Theta_1(\varepsilon x, \varepsilon), \quad \varphi_\varepsilon(x) = \varepsilon \Theta_2(\varepsilon x, \varepsilon),$$

where  $\Theta_1$  and  $\Theta_2$  satisfy:

$$\exists \delta > 0, \forall \alpha \geq 0, \exists C_\alpha > 0, \forall (x, \varepsilon) \in \mathbb{R} \times (0, \varepsilon_0), \quad |(\partial_x^\alpha \Theta_1)(x, \varepsilon)| \leq C_\alpha e^{-\delta|x|}$$

and

$$\exists \delta > 0, \forall \alpha \geq 1, \exists C_\alpha > 0, \forall (x, \varepsilon) \in \mathbb{R} \times (0, \varepsilon_0), \quad |(\partial_x^\alpha \Theta_2)(x, \varepsilon)| \leq C_\alpha e^{-\delta|x|}.$$

The functions  $\Theta_1(x, \varepsilon)$  and  $\Theta_2(x, \varepsilon)$  have smooth expansions in  $\varepsilon$ .

One has that

$$\Theta_1(\xi, 0) = -\cosh^{-2}\left(\frac{\xi}{2(\beta - 1/3)^{1/2}}\right),$$

which reminds us the KdV soliton.

## Statement of the result

Set

$$M(t, x) := Q_{c_1}(x - c_1 t) + Q_{c_2}(x - h - c_2 t).$$

where  $h > 0$ .

**Theorem 2** (<http://arxiv.org/abs/1304.5263>)

Let us fix  $s \geq 0$ . Suppose that the speeds  $c_1 < c_2$  satisfy

$$\frac{gH}{c_j^2} = 1 + \varepsilon_j^2, \quad \frac{b}{Hc_j^2} > \frac{1}{3}, \quad j = 1, 2.$$

Then there exists  $\varepsilon^*$  such that for  $\varepsilon_1, \varepsilon_2 \in (0, \varepsilon^*]$  and  $h$  sufficiently large, we have that there exists a (semi) global solution  $U(t) = (\eta(t), \varphi(t))$ ,  $t \geq 0$  to the water-wave system satisfying

$$U \in \mathcal{C}_b([0, \infty); H^s(\mathbb{R}) \times H^s(\mathbb{R}))$$

and

$$\lim_{t \rightarrow +\infty} \|U(t) - M(t)\|_{H^s \times H^s} = 0.$$

## Comments

- This result is inspired by previous works on simplified model equations such as the KdV, NLS or Hartree equations. Most notably, the works by Merle (1990), Martel (2005), Krieger-Martel-Raphaël (2009) and Combet (2010).
- One can take  $h = 0$  but then the solution is defined only on  $[T_0, +\infty)$ ,  $T_0 \gg 1$ .
- The behavior of  $U(t)$  for  $t \leq 0$  is unclear. One may wish to expect that it is globally defined. In a regime  $c_1 \sim c_2$  one may expect to perform the "finite box" analysis of the recent work by Martel-Merle.
- The uniqueness of  $U(t)$  is unclear.
- Similarly, one can construct a  $k$ -soliton for  $k > 2$ .

## Scheme of the proof

- The proof relies on the following ingredients :
  1. Consistency of  $M$  with the equation.
  2. Estimate for the possible growth of the linearization about  $M$  (a "stability" property).
  3. Quasi-linear energy estimates.
- Ingredient 1 uses in an essential way the nature of the fluid domain.
- Ingredient 2 relies on a stability analysis by Mielke.
- Ingredient 3 was already done in a previous work with F. Rousset on the transverse stability of solitary waves.
- With the three ingredients in hand, one concludes by invoking the Grenier argument.
- This scheme seems to apply to all previously studied situations. We hope that it may be extended to the case without surface tension ( $b = 0$ ). However in this case Ingredient 2 would rely on different arguments developed recently by Pego-Sun.

## Ingredient 1

- Denote schematically by  $WW$  the water waves equation. Then for a suitable norm  $\|\cdot\|$ ,

$$WW(M) = R, \quad \|R\| \lesssim e^{-\varepsilon_0 t} e^{-\varepsilon_0 h}, \quad \varepsilon_0 > 0.$$

- The key point to get this property is the following statement.

### **Proposition 3**

*Assume that  $\psi \in C_b^\infty(\mathbb{R})$  has the decay property :*

$$\exists d > 0, \forall \alpha \in \mathbb{N}, \alpha \geq 1, \exists C_\alpha, \forall x \in \mathbb{R}, |\partial_x^\alpha \psi(x)| \leq C_\alpha e^{-d|x|}.$$

*Then for  $\eta \in H^\infty(\mathbb{R})$  with  $H + \eta \geq c_0 > 0$ ,  $G[\eta]\psi$  has an exponential decay, that is, for any  $\alpha \geq 0$ , there exist a constant  $C_\alpha$  depending on  $\alpha$  and  $0 < \epsilon < d$  independent of  $\alpha$  such that for every  $x \in \mathbb{R}$ ,*

$$\left| \partial_x^\alpha (G[\eta]\psi)(x) \right| \leq C_\alpha e^{-\epsilon|x|}.$$

- The above result uses in an essential way that the fluid domain is bounded in the  $z$  direction (we use a Poincaré inequality).
- The statement does not hold in the case of an infinite bottom (singularity at the low frequencies affects the exponential decay).



## Ingredient 2 (preliminaries)

Set  $\delta = e^{-\varepsilon_0 h}$ . We look for the solution  $U$  under the form :

$$U = M + \delta v_1 + \delta^2 v_2 + \cdots \delta^N v_N + w.$$

Denote by  $L$  the linearized operator about  $M$  in the water waves equation. Then the equation for  $U$  can be reformulated as

$$\begin{aligned}(\partial_t + L)v_1 &= \delta^{-1}R, \\(\partial_t + L)v_2 &= Q_2(v_1), \\(\partial_t + L)v_3 &= Q_3(v_1, v_2), \\&\dots \\(\partial_t + L)v_N &= Q_N(v_1, v_2, \dots, v_{N-1}),\end{aligned}$$

plus an equation for  $w$ .

Ingredient 2 (statement and construction of  $v_j, j \geq 1$ )

- Denote by  $S(t, \tau)$  resolution operator associated to  $\partial_t + L$ . Then the key (and most difficult) point in the proof is there are  $\|\cdot\|_X$  and  $\|\cdot\|_{X_0}$  such that

$$\|S(t, \tau)(f)\|_X \lesssim h^{\frac{1}{4}} e^{\frac{\varepsilon_0}{2}|t-\tau|} \|f\|_{X_0}.$$

In fact,  $\frac{\varepsilon_0}{2}$  can be replaced by any positive constant and  $h^{\frac{1}{4}}$  is a harmless loss which probably may be avoided.

- Now, we define  $v_1$  as

$$v_1(t) = \int_t^\infty S(t, \tau)(\delta^{-1}R(\tau))d\tau.$$

Then

$$\|v_1(t)\|_X \lesssim h^{\frac{1}{4}} \int_t^\infty e^{\frac{\varepsilon_0}{2}(\tau-t)} e^{-\varepsilon_0\tau} d\tau \lesssim h^{\frac{1}{4}} e^{-\varepsilon_0 t}.$$

Ingredient 2 (construction of  $v_j$ ,  $j \geq 1$ , sequel)

- Next, we define  $v_2$  as

$$v_2(t) = \int_t^\infty S(t, \tau)(Q_2(v_1(\tau)))d\tau.$$

Then

$$\|v_2(t)\|_X \lesssim h^{\frac{3}{4}} \int_t^\infty e^{\frac{\varepsilon_0}{2}(\tau-t)} e^{-2\varepsilon_0\tau} d\tau \lesssim h^{\frac{3}{4}} e^{-2\varepsilon_0 t}.$$

- We now define similarly  $v_3, v_4, \dots$  and we have that

$$\|v_j(t)\|_X \lesssim h^{\frac{2j-1}{4}} e^{-j\varepsilon_0 t}, \quad j \geq 1.$$

- As a consequence the equation for  $w$  will have a strongly decaying source term.

Ingredient 3 (energy estimates and construction of  $w$ )

- Let  $(T_n)_{n=1}^{\infty}$  be a sequence tending to  $+\infty$ . We construct solutions  $w_n$  of the equation for  $w$  on  $[0, T_n]$  with  $w_n(T_n) = 0$ .
- $w_n$  enjoys the following energy estimate : for a suitable  $\|\cdot\|$ ,

$$\|w_n(t)\|^2 \lesssim \left( C + C_N \delta^{\frac{1}{2}} + \sup_{t \leq \tau \leq T_n} \|w_n(\tau)\| \right)^{100} \left( \int_t^{T_n} \|w_n(\tau)\|^2 d\tau + C_N e^{-2(N+1)\varepsilon_0 t} \right)$$

- We take first  $N \gg 1$  and then  $\delta \ll 1$  so that

$$2(N+1)\varepsilon_0 > \left( C + C_N \delta^{\frac{1}{2}} + 1 \right)^{100}.$$

- Thus, we can rewrite the energy estimate as follows

$$\frac{d}{dt} \left[ - e^{(C+C_N\delta^{\frac{1}{2}}+1)^{100}t} \int_t^{T_n} \|w_n(\tau)\|^2 d\tau \right] \lesssim e^{[(C+C_N\delta^{\frac{1}{2}}+1)^{100}-2(N+1)\varepsilon_0]t}$$

Ingredient 3 (energy estimates and construction of  $w$ , sequel)

- We integrate between  $t$  and  $T_n$  and we get

$$\int_t^{T_n} \|w_n(\tau)\|^2 d\tau \lesssim e^{-2(N+1)\varepsilon_0 t}$$

and therefore

$$\|w_n(t)\|^2 \lesssim e^{-2(N+1)\varepsilon_0 t}, \quad t \in [0, T_n]$$

- We conclude by a compactness argument. Extend  $w_n(t)$  by zero for  $t > T_n$  and fix  $\psi \in C_0^\infty(-1/2, 1/2)$  such that  $\psi = 1$  on  $(-1/4, 1/4)$ . Then we apply a classical compactness argument to the sequence

$$\left( \psi(t/T_n) w_n(t) \right)_{n \geq 1}, \quad t \geq 0.$$

- The limit object is  $w$  and the multi-soliton is constructed.

On the estimate for  $S(t, \tau)$

- The natural energy space for our problem is the space  $X$ , defined for  $U = (U_1, U_2)$  as

$$\|U\|_X^2 = \|U_1\|_{H^1}^2 + \|(1 - \partial_x^2)^{-\frac{1}{4}} \partial_x U_2\|_{L^2}^2.$$

- Denote by  $\Lambda$  the linearization of the energy  $E$  about a solitary wave  $Q_c$ . Then, according to the general Grillakis-Shatah-Strauss scheme one may expect the estimate

$$(\Lambda U, U) \gtrsim \|U\|_X^2, \quad (U, \partial_x Q_c) = (U, J^{-1} \partial_x Q_c) = 0, \quad J = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}. \quad (2)$$

But  $(U, \partial_x Q_c)$  takes different values for  $U = (0, 1)$  and  $U = (0, 2)$  and in fact one may show that (2) is wrong.

- Following Mielke, we can replace  $(U, \partial_x Q_c)$  by  $(U_1, \eta_c)$  and still get (2).
- With this estimate in hand, we get that the semigroup associated to  $J\Lambda$  grows as  $t$  (like for KdV). One makes a direct sum decomposition of  $\text{span}(\partial_x Q_c, J\partial_x Q_c)$  with a space  $E$  which satisfies the modified orthogonality conditions.

On the estimate for  $S(t, \tau)$  (sequel)

- In order to estimate  $S(t, \tau)$ , we use energy functional of the type :

$$E(U(t)) = -(JLU, U) - c_1(\partial_x J(\chi_1 U), \chi_1 U) - c_2(\partial_x J(\chi_2 U), \chi_2 U),$$

where we recall that  $L$  is the linearized about  $M$  operator in the water waves system and  $\chi_1$  and  $\chi_2$  localize near  $Q_{c_1}$  and  $Q_{c_2}$ .

- The first term in  $E$  corresponds to the energy conservation, the second and the third one to the conservation of the momentum.
- For suitable quantities  $x(t) = x(U(t))$  of Sobolev type, we get estimates of type  $\dot{x}(t) \lesssim \delta(h)x(t)$ , where  $\delta(h) \rightarrow 0$  as  $h$  goes to infinity.

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